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He received a diploma in Plasma Physics from the Masaryk University in Brno, Czechia in 2008 and a PhD. degree in Metrology from Slovak Technical University in Bratislava, Slovakia in 2013. The topic of his thesis work was: Study of Mass Standards in Vacuum. He has been working in Czech Metrology Institute since 2008 as a full time Metrologist. He started working on his diploma thesis on Volume Measurements of Weights in 2006. He became Head of Primary Mass Metrology Department in 2019. He had been a coordinator of the EMPIR project entitled Improvement of the Realisation of the Mass Scale (2020-2023).



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#### METROLOGY SYMPOSIUM DIGITALIZATION AND AUTOMATION IN MASS METROLOGY

**Third Edition: Future and New Solutions** 



### Calibration guide for dissemination of mass



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- EMPIR project 19RPT02 "Improvement of the realisation of the mass scale"
- Started in 2020, finished in 2023
- 11 project partners
  - Lead by CMI

## **Calibration guide for dissemination of mass**

- CMI (Czechia) project leader
- BEV-PTP (Austria) leader of WP1
- IMBiH (Bosnia and Herzegovina) leader of WP2
- INRIM (Italy) leader of WP3
- BIM (Bulgaria)
- BRML (Romania)

- DMDM (Serbia)
- NSAI (Ireland)
- SMD (Belgium)
- ME-BoM (North Macedonia)
- NSC-IM (Ukraine)



- Analysis of calibration methods for the realisation and dissemination of the mass scale
- Development and implementation of calibration methods to realise, improve and maintain mass scale
- Development of mathematical and statistical tools and software solutions
- Euramet draft guide for the realisation of the mass scale
- Individual strategies for long-term operation



- Elements and influencing quantities of the calibration
- Methods of the measurement and weighing designs
- Mathematical models, reliability of and correlation of the measurement results
- Uncertainty, influencing factors and calculations
- Typical example
  - Dissemination of weight set from 1kg reference
  - Dissemination with more reference weights of different nominal masses

• Starting with equation for direct comparison

$$\Delta m = \delta m \left( 1 - \frac{\rho_{a_j}}{\rho_{adj}} \right) + \rho_a (\sum V_B - \sum V_A)$$

• Corrections to temperature

$$V = V_{20} (1 + \alpha (T - 20))$$

• Corrections to center of gravity

$$\delta m_G = m_N \left[ \frac{\Delta g}{g} (h_A - h_B) \right]$$



• System of equations in matrix notation

$$X_w m = y_w + \epsilon$$

- Evaluation of calibration scheme by least square methods
  - Gauss-Markov approach
  - Lagrange multipliers method
- Mass of the reference weights added as separate lines
- Solution in form like

$$\widehat{m} = \left(X_w^T \Psi_y^{-1} X_w\right)^{-1} X_w^T \Psi_y^{-1} y_w$$

- Uncertainty considerations
  - Standard deviation of the measurements
  - Uncertainty of volume, air density, center of gravity etc.
- Some units can and should be considered correlated
  - Air density usually measured by the same devices (p, h, T)
  - Mass and volume of the reference

$$u(m,V) = \rho_{a_E} u^2(V)$$

• When more reference weights used, correlation from the current status of kilogram definition arises

- Software RealMass
  - Developed by INRIM
- Inputs and outputs in Excel
- Correlations, uncertainties, type of stacking etc.

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- Following presentations
  - Zoltan Zelenka Revisiting weighing designs
  - Bianka Mangutova Stoilkovska Mass metrology needs in emerging institutes

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# Thank you for your attention

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